SIEMENS

Data sheet

6ES7517-3AP00-0AB0

SIMATIC S7-1500, CPU 1517-3 PN/DP, CENTRAL PROCESSING UNIT WITH WORKING MEMORY 2 MB FOR PROGRAM AND 8 MB FOR DATA, 1. INTERFACE: PROFINET IRT WITH 2 PORT SWITCH, 2. INTERFACE: PROFINET RT, 3. INTERFACE: PROFIBUS, 2 NS BIT-PERFORMANCE, SIMATIC MEMORY CARD NECESSARY



| General information | |
|---|------------------|
| Product type designation | CPU 1517-3 PN/DP |
| HW functional status | FS04 |
| Firmware version | V2.0 |
| Engineering with | |
| STEP 7 TIA Portal configurable/integrated as of version | V14 |
| Configuration control | |
| via dataset | Yes |
| Display | |
| Screen diagonal (cm) | 6.1 cm |
| Control elements | |
| Number of keys | 6 |
| Mode selector switch | 1 |
| Supply voltage | |
| Type of supply voltage | 24 V DC |
| permissible range, lower limit (DC) | 19.2 V |
| | |

| permissible range, upper limit (DC) | 28.8 V |
|---|---|
| Reverse polarity protection | Yes |
| Mains buffering | |
| Mains/voltage failure stored energy time | 5 ms |
| Input current | |
| Current consumption (rated value) | 1.55 A |
| Inrush current, max. | 2.4 A; Rated value |
| l²t | 0.02 A²·s |
| Power | |
| Power consumption from the backplane bus (balanced) | 30 W |
| Infeed power to the backplane bus | 12 W |
| Power loss | |
| Power loss, typ. | 24 W |
| | |
| Memory Charles (CIMATIC | |
| Number of slots for SIMATIC memory card | 1 |
| SIMATIC memory card required | Yes |
| Work memory | 0.18 |
| integrated (for program) | 2 Mbyte |
| • integrated (for data) | 8 Mbyte |
| Load memory | |
| Plug-in (SIMATIC Memory Card), max. | 32 Gbyte |
| Backup | |
| maintenance-free | Yes |
| CPU processing times | |
| for bit operations, typ. | 2 ns |
| for word operations, typ. | 3 ns |
| for fixed point arithmetic, typ. | 3 ns |
| for floating point arithmetic, typ. | 12 ns |
| CPU-blocks | |
| Number of elements (total) | 10 000; Blocks (OB, FB, FC, DB) and UDTs |
| DB | |
| Number range | 1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999 |
| • Size, max. | 8 Mbyte; For non-optimized block accesses, the max. size of the DB is 64 KB |
| FB | |
| Number range | 0 65 535 |
| • Size, max. | 512 kbyte |
| FC | |
| | |

| Number range | 0 65 535 |
|--|--|
| • Size, max. | 512 kbyte |
| OB | |
| • Size, max. | 512 kbyte |
| Number of free cycle OBs | 100 |
| Number of time alarm OBs | 20 |
| Number of delay alarm OBs | 20 |
| Number of cyclic interrupt OBs | 20; With minimum OB 3x cycle of 100 μs |
| Number of process alarm OBs | 50 |
| Number of DPV1 alarm OBs | 3 |
| Number of isochronous mode OBs | 2 |
| Number of technology synchronous alarm OBs | 2 |
| Number of startup OBs | 100 |
| Number of asynchronous error OBs | 4 |
| Number of synchronous error OBs | 2 |
| Number of diagnostic alarm OBs | 1 |
| Nesting depth | |
| per priority class | 24 |
| | |
| Counters, timers and their retentivity S7 counter | |
| Number | 2 048 |
| Retentivity | 20.0 |
| — adjustable | Yes |
| IEC counter | |
| Number | Any (only limited by the main memory) |
| Retentivity | , (a. 5) - 12-12-12-12-13-13-13-13-13-13-13-13-13-13-13-13-13- |
| — adjustable | Yes |
| S7 times | |
| Number | 2 048 |
| Retentivity | |
| — adjustable | Yes |
| IEC timer | |
| • Number | Any (only limited by the main memory) |
| Data areas and their retentivity | |
| Flag | |
| Number, max. | 16 kbyte |
| Number of clock memories | 8; 8 clock memory bits, grouped into one clock memory byte |
| Data blocks | |
| Retentivity adjustable | Yes |
| Retentivity preset | No |
| Local data | |
| | |

| • per priority class, max. | 64 kbyte; max. 16 KB per block |
|---|---|
| Address area | |
| Number of IO modules | 16 384; max. number of modules / submodules |
| I/O address area | |
| • Inputs | 32 kbyte; All inputs are in the process image |
| Outputs | 32 kbyte; All outputs are in the process image |
| per integrated IO subsystem | |
| — Inputs (volume) | 16 kbyte; 16 KB via the integrated PROFINET IO interface, 8 KB via the integrated DP interface |
| — Outputs (volume) | 16 kbyte; 16 KB via the integrated PROFINET IO interface, 8 KB via the integrated DP interface |
| per CM/CP | |
| — Inputs (volume) | 8 kbyte |
| — Outputs (volume) | 8 kbyte |
| Subprocess images | |
| Number of subprocess images, max. | 32 |
| Hardware configuration | |
| Number of distributed IO systems | 64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link) |
| Number of DP masters | |
| • integrated | 1 |
| • Via CM | 8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total |
| Number of IO Controllers | |
| • integrated | 2 |
| ● Via CM | 8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total |
| Rack | |
| Modules per rack, max. | 32; CPU + 31 modules |
| Number of lines, max. | 1 |
| PtP CM | |
| Number of PtP CMs | the number of connectable PtP CMs is only limited by the number of available slots |
| Time of day | |
| Clock | |
| • Type | Hardware clock |
| Backup time | 6 wk; At 40 °C ambient temperature, typically |
| Deviation per day, max. | 10 s; Typ.: 2 s |
| Operating hours counter | |
| • Number | 16 |

| Clock synchronization | |
|---|--|
| • supported | Yes |
| • to DP, master | Yes |
| ● in AS, master | Yes |
| • in AS, slave | Yes |
| on Ethernet via NTP | Yes |
| | |
| Interfaces Number of PROFINET interfaces | 2 |
| Number of PROFIBUS interfaces | 1 |
| | |
| 1. Interface | |
| Interface types | |
| Number of ports | 2 |
| • integrated switch | Yes |
| • RJ 45 (Ethernet) | Yes; X1 |
| Functionality | Voo |
| PROFINET IO Controller | Yes |
| PROFINET IO Device | Yes |
| SIMATIC communication | Yes |
| Open IE communication | Yes |
| Web server | Yes |
| Media redundancy | Yes |
| PROFINET IO Controller | |
| Services | V. |
| — PG/OP communication | Yes |
| — S7 routing | Yes |
| — Isochronous mode | Yes |
| Open IE communication | Yes |
| — IRT | Yes |
| — MRP | Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50 |
| — MRPD | Yes; Requirement: IRT |
| — PROFlenergy | Yes |
| Prioritized startup | Yes; Max. 32 PROFINET devices |
| Number of connectable IO Devices, max. | 512; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET |
| — Of which IO devices with IRT, max. | 64 |
| Number of connectable IO Devices for RT, max. | 512 |
| — of which in line, max. | 512 |
| Number of IO Devices that can be simultaneously activated/deactivated, max. | 8; in total across all interfaces |
| Simultaneously activated/deactivated, max. | |

| Number of IO Devices per tool, max. | 8 |
|--|---|
| — Updating times | The minimum value of the update time also depends on |
| ., | communication share set for PROFINET IO, on the number of IO |
| | devices, and on the quantity of configured user data |
| Update time for IRT | |
| — for send cycle of 250 μs | $250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 μs of the isochronous OB is decisive |
| — for send cycle of 500 μs | 500 μs to 8 ms |
| — for send cycle of 1 ms | 1 ms to 16 ms |
| — for send cycle of 2 ms | 2 ms to 32 ms |
| — for send cycle of 4 ms | 4 ms to 64 ms |
| With IRT and parameterization of "odd" | Update time = set "odd" send clock (any multiple of 125 µs: 375 |
| send cycles | μs, 625 μs 3 875 μs) |
| Update time for RT | |
| — for send cycle of 250 μs | 250 μs to 128 ms |
| — for send cycle of 500 μs | 500 μs to 256 ms |
| — for send cycle of 1 ms | 1 ms to 512 ms |
| — for send cycle of 2 ms | 2 ms to 512 ms |
| — for send cycle of 4 ms | 4 ms to 512 ms |
| PROFINET IO Device | |
| Services | |
| — PG/OP communication | Yes |
| — S7 routing | Yes |
| — Isochronous mode | No |
| — Open IE communication | Yes |
| — IRT | Yes |
| — MRP | Yes |
| — MRPD | Yes; Requirement: IRT |
| — PROFlenergy | Yes |
| Shared device | Yes |
| Number of IO Controllers with shared | 4 |
| device, max. | |
| 2. Interface | |
| Interface types | |
| Number of ports | 1 |
| • integrated switch | No |
| • RJ 45 (Ethernet) | Yes; X2 |
| Functionality | |
| PROFINET IO Controller | Yes |
| PROFINET IO Device | Yes |
| SIMATIC communication | Yes |

| Open IE communication | Yes |
|---|--|
| Web server | Yes |
| Media redundancy | No |
| PROFINET IO Controller | |
| Services | |
| — PG/OP communication | Yes |
| — S7 routing | Yes |
| — Isochronous mode | No |
| Open IE communication | Yes |
| — IRT | No |
| — MRP | No |
| — PROFlenergy | Yes |
| Prioritized startup | No |
| Number of connectable IO Devices, max. | 128; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET |
| Number of connectable IO Devices for RT, max. | 128 |
| — of which in line, max. | 128 |
| Number of IO Devices that can be simultaneously activated/deactivated, max. | 8; in total across all interfaces |
| Number of IO Devices per tool, max. | 8 |
| — Updating times | The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data |
| Update time for RT | |
| — for send cycle of 1 ms | 1 ms to 512 ms |
| PROFINET IO Device | |
| Services | |
| — PG/OP communication | Yes |
| — S7 routing | Yes |
| — Isochronous mode | No |
| — Open IE communication | Yes |
| – IRT | No |
| — MRP | No |
| — MRPD | No |
| — PROFlenergy | Yes |
| — Prioritized startup | No |
| — Shared device | Yes |
| Number of IO Controllers with shared | 4 |
| device, max. | |
| 3. Interface | |

3. Interface

Interface types

| Number of ports | 1 |
|---|---|
| • RS 485 | Yes; X3 |
| Functionality | |
| PROFIBUS DP master | Yes |
| PROFIBUS DP slave | No |
| SIMATIC communication | Yes |
| nterface types | |
| RJ 45 (Ethernet) | |
| • 100 Mbps | Yes |
| Autonegotiation | Yes |
| Autocrossing | Yes |
| Industrial Ethernet status LED | Yes |
| RS 485 | |
| • Transmission rate, max. | 12 Mbit/s |
| Protocols | |
| Number of connections | |
| Number of connections, max. | 320; via integrated interfaces of the CPU and connected CPs / CMs |
| Number of connections reserved for ES/HMI/web | 10 |
| Number of connections via integrated interfaces | 160 |
| Number of S7 routing paths | 64; in total, only 16 S7-Routing connections are supported via PROFIBUS |
| SIMATIC communication | |
| S7 communication, as server | Yes |
| S7 communication, as client | Yes |
| • User data per job, max. | See online help (S7 communication, user data size) |
| Open IE communication | |
| • TCP/IP | Yes |
| — Data length, max. | 64 kbyte |
| several passive connections per port, supported | Yes |
| • ISO-on-TCP (RFC1006) | Yes |
| — Data length, max. | 64 kbyte |
| - | |

Yes

No Yes

Yes Yes

1 472 byte

• UDP

• DHCP

SNMPDCP

• LLDP Web server

— Data length, max.

| • HTTP | Yes; Standard and user pages |
|---|--|
| • HTTPS | Yes; Standard and user pages |
| PROFIBUS DP master | |
| Number of connections, max. | 48; for the integrated PROFIBUS DP interface |
| Services | |
| — PG/OP communication | Yes |
| — S7 routing | Yes |
| Data record routing | Yes |
| — Isochronous mode | Yes |
| — Equidistance | Yes |
| — Number of DP slaves | 125; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET |
| Activation/deactivation of DP slaves | Yes |
| OPC UA | |
| OPC UA Server | Yes; Data access (read, write, subscribe), runtime license required |
| Application authentication | Yes |
| — Security policies | Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256 |
| User authentication | "anonymous" or by user name & password |
| Further protocols | |
| • MODBUS | Yes; MODBUS TCP |
| Media redundancy | |
| Switchover time on line break, typ. | 200 ms; For MRP, bumpless for MRPD |
| Number of stations in the ring, max. | 50 |
| Isochronous mode | |
| Isochronous operation (application synchronized up to terminal) | Yes; With minimum OB 6x cycle of 250 µs |
| Equidistance | Yes |
| | |
| S7 message functions Number of login stations for message functions, max. | 32 |
| Block related messages | Yes |
| Number of configurable alarms, max. | 10 000 |
| Number of simultaneously active alarms in alarm | 10 000 |
| pool | |
| Number of reserved user alarms | 1 000 |
| Number of reserved alarms for system diagnostics | 200 |
| Number of reserved alarms for Motion Control technology objects | 160 |
| Test commissioning functions | |

| Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track program; selection guide via the TIA Selection Tool or SIZER 10 240 40 40 80 20 160 | Joint commission (Team Engineering) | Yes; Parallel online access possible for up to 10 engineering |
|--|---|---|
| Single step Status/control Status/control variable Status/control variables Ves Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters Number of variables, max. — of which status variables, max. — of which control variables, max. — of which control variables, max. — of which control variables, max. — of which operations with the proof variables, max. Peripheral inputs/outputs Peripheral inputs/outputs Peripheral inputs/outputs Peripheral inputs/outputs Number of variables, max. — of which powerfail-proof Praces Number of configurable Traces Per RRNINSTOP LED Per RRNINSTOP LED Per RRNINSTOP LED Per RRNINSTOP LED Per Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per syeed-controlled axis — per syechronous axis — per synchronous axis — per synchronous axis — per synchronous axis — per output cam — per cam track 100 Pass Ves Ves Ves Ves Ves Ves Ves | | systems |
| Status/control variable Variables Number of variables, max. — of which status variables, max. — of which control variables, max. Peripheral inputs/outputs Peripheral inputs/outp | Status block | Yes; Up to 16 simultaneously (in total across all ES clients) |
| Status/control variable Variables Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters Number of variables, max. — of which status variables, max. — of which control variables, max. — of which status variables, max. — of which control variables, max. — of which control variables, max. — of which control variables, max. — Peripheral inputs/outputs Peripheral inputs/outpu | Single step | No |
| Variables Number of variables, max. of which status variables, max. of which control variables, max. Peripheral inputs/outputs Number of variables, max. of which control variables, max. Peripheral inputs/outputs Number of variables, max. Peripheral inputs/outputs Number of variables, max. Peripheral inputs/outputs Number of variables, max. of which powerfail-proof Number of entries, max. of which powerfail-proof Number of configurable Traces Number of available Motion Control Yes Pes Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources of reper speed-controlled axis per speed-controlled axis per speed-controlled axis per positioning axis per external encoder per output cam per cam track 160 per cam track 160 | Status/control | |
| Number of variables, max. — of which status variables, max. — of which status variables, max. — of which control variables, max. — of which control variables, max. — of which control variables, max. Peripheral inputs/outputs • Number of variables, max. 200 Diagnostic buffer • present • Number of entries, max. — of which powerfail-proof Traces • Number of configurable Traces • RUN/STOP LED • ERROR LED • ERROR LED • MAINT LED • Connection display LINK TX/RX Yes Supported technology objects Motion Control • Number of available Motion Control resources for technology objects (except cam disks) • Required Motion Control resources — per speed-controlled axis — per positioning axis — per positioning axis — per positioning axis — per positioning axis — per output cam — per cam track 160 — per output cam — per cam track 160 | Status/control variable | Yes |
| - of which status variables, max. 200; per job - of which control variables, max. 200; per job Forcing • Forcing, variables • Number of variables, max. 200 Diagnostic buffer • present • Number of entries, max. 3 200 - of which powerfail-proof 1 000 Traces • Number of configurable Traces 8; Up to 512 KB of data per trace are possible Interrupts/diagnostics/status information Diagnostics indication LED • RUN/STOP LED Yes • MAINT LED Yes • MAINT LED Yes • Connection display LINK TX/RX Supported technology objects Motion Control • Number of available Motion Control resources for technology objects (except cam disks) • Required Motion Control resources for technology objects (except cam disks) • Required Motion Control resources - per speed-controlled axis - per synchronous axis - per external encoder - per output cam - per cam track 100 200 Peripheral inputs/outputs Peripheral inputs/outputs Peripheral inputs/outputs 9 Number of variables, max. 200 Peripheral inputs/outputs 9 Ves 9 Supported trace are possible 100 100 Traces 100 Yes 9 Supported technology objects 10 240 10 240 10 240 10 240 | Variables | |
| Forcing Forcing, variables Number of variables, max. Peripheral inputs/outputs Number of variables, max. Persent Number of entries, max. Of which powerfail-proof Number of configurable Traces Number of explain the trace are possible Personal LED Yes Number of explain the trace are possible Number of configurable Traces Number of available Motion Control resources for technology objects Number of available Motion Control resources of technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per speed-controlled axis — per synchronous axis — per external encoder — per output cam — per cam track 160 Number of available Motion Control resources Number of configuration Number of configuration Number of config | Number of variables, max. | |
| Forcing Forcing, variables Number of variables, max. Diagnostic buffer Persent Present Pres | — of which status variables, max. | 200; per job |
| Forcing, variables Number of variables, max. Peripheral inputs/outputs Number of variables, max. Present Present Indicate the first of variables, max. Persont Present Present Present Number of entries, max. Of which powerfail-proof Traces Number of configurable Traces Right to 512 KB of data per trace are possible Number of configurable Traces Right to 512 KB of data per trace are possible Number of configurable Traces Right to 512 KB of data per trace are possible Number of configurable Traces Right to 512 KB of data per trace are possible Number of configurable Traces Prese Pres | — of which control variables, max. | 200; per job |
| Number of variables, max. Diagnostic buffer present present Number of entries, max. of which powerfail-proof 1 000 Traces Number of configurable Traces Number of available Motion Control resources for technology objects Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources - per speed-controlled axis - per positioning axis - per positioning axis - per synchronous axis - per external encoder - per output cam - per cam track 160 | Forcing | |
| Diagnostic buffer • present • Number of entries, max. — of which powerfail-proof Traces • Number of configurable Traces • Number of configurable Traces • Number of configurable Traces • Number of configurable Traces • RUP to 512 KB of data per trace are possible Interrupts/diagnostics/status information Diagnostics indication LED • RUN/STOP LED • REROR LED • MAINT LED • Connection display LINK TX/RX Yes Supported technology objects Motion Control • Number of available Motion Control resources for technology objects (except cam disks) • Required Motion Control resources — per speed-controlled axis — per positioning axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track 1000 Yes Yes Yes Yes Yes Yes Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER 10 240 | Forcing, variables | Peripheral inputs/outputs |
| Present Number of entries, max. of which powerfail-proof Traces Number of configurable Traces Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per synchronous axis per external encoder per output cam per cam track Number of evan disks Number of available Motion Control resources 160 Number of available Motion Control resources Number of available Motion C | Number of variables, max. | 200 |
| Number of entries, max. — of which powerfail-proof Traces Number of configurable Traces Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per cam track Number of evaluation LED Yes Number of available Motion Control resources for technology objects (except cam disks) Number of available Motion Control resources Number of available Motion Control resour | Diagnostic buffer | |
| — of which powerfail-proof Traces Number of configurable Traces Number of configurable Traces Styp to 512 KB of data per trace are possible Number of configurable Traces Reference to the possible of the public to the pub | • present | Yes |
| Traces Number of configurable Traces S; Up to 512 KB of data per trace are possible Interrupts/diagnostics/status information Diagnostics indication LED RUN/STOP LED REROR LED MAINT LED Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track 160 | Number of entries, max. | 3 200 |
| Number of configurable Traces 8; Up to 512 KB of data per trace are possible nterrupts/diagnostics/status information Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track 8; Up to 512 KB of data per trace are possible Yes Number of data per trace are possible Yes Yes Yes Yes Yes Yes Yes Y | — of which powerfail-proof | 1 000 |
| nterrupts/diagnostics/status information Diagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track 160 Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER 10 240 40 40 90 90 90 90 90 90 90 | Traces | |
| Piagnostics indication LED RUN/STOP LED ERROR LED MAINT LED Connection display LINK TX/RX Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track Pes Yes Yes Yes Yes Yes Yes Yes | Number of configurable Traces | 8; Up to 512 KB of data per trace are possible |
| RUN/STOP LED ERROR LED MAINT LED Connection display LINK TX/RX Yes Supported technology objects Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per positioning axis per positioning axis per external encoder per output cam per cam track Yes Yes Yes Yes Yes Yes Yes Ye | nterrupts/diagnostics/status information | |
| ERROR LED MAINT LED MAINT LED Connection display LINK TX/RX Yes Supported technology objects Motion Control Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per positioning axis — per external encoder — per output cam — per cam track 160 | Diagnostics indication LED | |
| MAINT LED Connection display LINK TX/RX Yes Motion Control Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track Yes Yes Yes Yes Yes Yes Yes Ye | RUN/STOP LED | Yes |
| Connection display LINK TX/RX Supported technology objects Motion Control | • ERROR LED | Yes |
| Supported technology objects Motion Control Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER 10 240 10 240 | MAINT LED | Yes |
| Motion Control Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track Yes; Note: The number of axes affects the cycle time of the PL program; selection guide via the TIA Selection Tool or SIZER 10 240 40 40 80 — per positioning axis 160 — per external encoder 160 | Connection display LINK TX/RX | Yes |
| Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track program; selection guide via the TIA Selection Tool or SIZER 10 240 40 80 90 160 160 160 160 | | |
| Number of available Motion Control resources for technology objects (except cam disks) Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 10 240 40 80 20 160 | Motion Control | Yes; Note: The number of axes affects the cycle time of the PLC |
| for technology objects (except cam disks) Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track 160 | | |
| Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track 160 | | 10 240 |
| per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track 40 80 20 160 | | |
| per positioning axis per synchronous axis per external encoder per output cam per cam track | · | 40 |
| per synchronous axis per external encoder per output cam per cam track | | |
| per external encoder per output cam per cam track | | |
| — per output cam— per cam track20160 | • | |
| — per cam track 160 | — per external encoder | |
| F 4. 5-11. | | |
| — per probe 40 | — per cam track | |
| | — per probe | 40 |
| Positioning axis | Positioning axis | |
| — Number of positioning axes at motioncontrol cycle of 4 ms (typical value) | | 70 |

| Number of positioning axes at motion control cycle of 8 ms (typical value) | 128 |
|--|--|
| Controller | |
| PID_Compact | Yes; Universal PID controller with integrated optimization |
| • PID_3Step | Yes; PID controller with integrated optimization for valves |
| • PID-Temp | Yes; PID controller with integrated optimization for temperature |
| Counting and measuring | |
| High-speed counter | Yes |

| Ambient conditions | |
|---|--|
| Ambient temperature during operation | |
| horizontal installation, min. | 0 °C |
| • horizontal installation, max. | 60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off |
| vertical installation, min. | 0 °C |
| • vertical installation, max. | 40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off |
| Ambient temperature during storage/transportation | |
| • min. | -40 °C |
| • max. | 70 °C |

| Configuration | |
|---|-------------------------------|
| Programming | |
| Programming language | |
| — LAD | Yes |
| — FBD | Yes |
| — STL | Yes |
| — SCL | Yes |
| — GRAPH | Yes |
| Know-how protection | |
| User program protection | Yes |
| Copy protection | Yes |
| Block protection | Yes |
| Access protection | |
| Password for display | Yes |
| Protection level: Write protection | Yes |
| Protection level: Read/write protection | Yes |
| Protection level: Complete protection | Yes |
| Cycle time monitoring | |
| • lower limit | adjustable minimum cycle time |
| • upper limit | adjustable maximum cycle time |

175 mm

Dimensions Width

| Height | 147 mm | |
|-----------------|------------|--|
| Depth | 129 mm | |
| Weights | | |
| Weight, approx. | 1 978 g | |
| last modified: | 12/06/2016 | |